



Form 1449 (Modified)

**Information Disclosure  
Statement By Applicant**

(Use Several Sheets if Necessary)

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**MAT-17**

Applicants:

**Devine, et al**

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Group

**3652**

**U.S. Patent Documents**

Examiner Initial	No.	Patent No.	Date	Patentee	Class	Sub-class	Filing Date
KM	A	5,534,231	7/9/1996	Savas			
KM	B	5,811,022	11/22/1998	Savas et al			
KM	C	5,855,681	1/5/1999	Maydan et al			
KM	D	5,964,949	10/12/1999	Savas			
	E						
	F						
	G						

**Foreign Patent or Published Foreign Patent Application**

Examiner Initial	No.	Document No.	Publication Date	Country or Patent Office	Class	Sub-class	Translation	
							Yes	No
	H							
	I							
	J							
	K							

**Other Documents**

Examiner Initial	No.	Author, Title, Date, Place (e.g. Journal) of Publication
KM	L	Shiller et al; Robot Path Planning with Obstacles, Actuator, Gripper, and Payload Constraints; December 1989; International Journal of Robotics Research, Vol 8, No 6, pp 3-18
KM	M	Shiller et al; Computation of Path Contained Time Optimal Motions with Dynamic Singularities; March 1992; Transactions of the ASME, Journal of Dynamic Systems, Measurements, and Control, vol 114, pp 34-40
KM	N	Mattson Technology, Inc; Aspen CVD Performance Specifications; Previously Cited in US Patent 5,855,681 filed November 18, 1996; Mattson Technology, Inc.
KM	O	Novellus, CVD Processing Brochure, Previously Cited in US Patent 5,855,681 filed November 18, 1996, Novellus
Examiner /Karla Moore/ (05/24/2007)		Date Considered 05/24/2007

Examiner: Initial citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.